# **BLP25RFE001 - User Guide**

Programing User Guide
Rev. 0.2 — 22 March 2018

**AMPLEON** 

**Application note** 

#### **Document information**

Info	Content
Keywords	RF heating
Abstract	User guide of the BLP25RFE001 software driver. Description of the public functions and how to use the source code.

## AN1505 - BLP25RFE001

**Programing User Guide** 

#### **Revision history**

Rev	Date	Description
1.0	27 Jan 2015	Creation
1.1	4 Feb 2015	Add flowcharts for initialization and devices synchronization
1.2	22 March 2018	Changed formatting

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#### 1. Introduction

This document contains a description of the public functions of the BLP25RFE001 software driver.

*Volcano* is the initial project nickname of the BLP25RFE001 product. In this document and the software driver, Volcano always refers to the BLP25RFE001 product.

## 2. Package contents

The driver package contains the following components:

- A header file containing the public functions of the driver
  - o Volcano.h
- A header file containing the private functions and internal data types of the driver
  - o Volcano\_local.h
- A source file containing the code of all the functions
  - o Volcano.c

## 3. Description of public functions of the driver

#### 3.1 Overview

The driver can be fully controlled by the following functions:

Volcano Open Volcano Close Volcano HwInit Volcano SetRF Volcano\_ResetSynchro Volcano SetSynchroMaster Volcano SetSynchroSlave Volcano SetPowerStateMode Volcano SetRFPhase Volcano SetRFAtten Volcano GetPowerStateMode Volcano GetAtrfPhase Volcano GetThermo Volcano Write Volcano Read Volcano ReadRegMap

## 3.2 Volcano\_Open

#### 3.2.1 Description

Initializes the driver instance. No hardware access is performed in this function. The function *Volcano\_Open* function must be called before *Volcano\_Hwlnit* (hardware initialization).

#### 3.2.2 Parameters

- tmUnitSelect\_t tUnit: Device unit number (for a single BLP25RFE001 device).
- tmUnitSelect\_t tUnitD: Device unit number (used only for OM15000 or SANGO board, otherwise to be set to 0).
- **SysDependency\_t** \*psSrvFunc: Structure containing the hardware access functions and the time functions.

#### 3.3 Volcano\_Close

## 3.3.1 Description

De-initializes the driver instance. Must be called before calling *Volcano\_Open* again if already initialized.

#### 3.3.2 Parameters

- tmUnitSelect t tUnit: Device unit number.

#### 3.4 Volcano\_Hwlnit

#### 3.4.1 Description

Initializes the hardware of the device matching the device unit number.

#### 3.4.2 Parameters

- tmUnitSelect t tUnit: Device unit number.
- Volcano\_\_ModeMS\_t uModeMS: Device role (Master or Slave).

#### 3.5 Volcano SetRF

## 3.5.1 Description

Tunes the device to the selected frequency in Hertz.

#### 3.5.2 Parameters

- tmUnitSelect t tUnit. Device unit number.
- UInt32 uLO: Local Oscillator frequency (in Hz).
- Bool bBlanking: PA in power down during SetRF.

## 3.6 Volcano\_ResetSynchro

#### 3.6.1 Description

Activates the LO\_CHAIN synchronization.

#### 3.6.2 Parameters

- tmUnitSelect ttUnit: Device unit number.

## 3.7 Volcano\_SetSynchroMaster

#### 3.7.1 Description

Activates the LO\_CHAIN synchronization for the master device.

## 3.7.2 Parameters

- tmUnitSelect\_t tUnit: Device unit number.

## 3.8 Volcano\_SetSynchroSlave

#### 3.8.1 Description

Activates the LO\_CHAIN synchronization for the slave device.

#### 3.8.2 Parameters

- tmUnitSelect t tUnit: Device unit number.

#### 3.9 Volcano SetPowerStateMode

#### 3.9.1 Description

Manages the power down state according to the desired state mode.

#### 3.9.2 Parameters

- tmUnitSelect\_t tUnit: Device unit number.
- Volcano\_PowerStateMode\_t PowerStateMode: Desired power state mode.

## 3.10 Volcano\_SetRFPhase

#### 3.10.1 Description

Tunes the RF output signal to the selected phase.

#### 3.10.2 Parameters

- tmUnitSelect\_t tUnit: Device unit number.
- UInt16 Phase: Phase value in degree.

## 3.11 Volcano\_SetRFAtten

## 3.11.1 Description

Tunes the attenuation of the RF output signal.

#### 3.11.2 Parameters

- tmUnitSelect ttUnit: Device unit number.
- UInt16 Atten: RF attenuation value in 1/256 dB steps.

#### 3.12 Volcano\_GetPowerStateMode

#### 3.12.1 Description

Get the current power state mode.

#### 3.12.2 Parameters

- tmUnitSelect\_t tUnit: Device unit number.
- Volcano\_PowerStateMode\_t \*pPowerStateMode: Pointer to the current power state mode.

#### 3.13 Volcano\_GetAtrfPhase

#### 3.13.1 Description

Launches and get back ATRF phase in steps of 1.4°.

#### 3.13.2 Parameters

- tmUnitSelect\_t tUnit: Device unit number.
- UInt32 \*pATRF\_Phase: Pointer to the ATRF phase in steps of 1.4°.

#### 3.14 Volcano GetAtrfPhase

#### 3.14.1 Description

Returns the IC temperature in degrees Celsius.

#### 3.14.2 Parameters

- tmUnitSelect ttUnit: Device unit number.
- UInt8 \* pThermo: Pointer to the IC temperature in degrees Celsius.

#### 3.15 Volcano Write

#### 3.15.1 Description

Writes in the device hardware registers.

#### 3.15.2 Parameters

- tmUnitSelect ttUnit: Device unit number.
- const **Volcano\_BitField\_t** \***pBitField**: Pointer to the device register field.
- UInt8 uData: Data to write.

#### 3.16 Volcano Read

#### 3.16.1 Description

Reads in the device hardware registers.

#### 3.16.2 Parameters

- tmUnitSelect\_t tUnit: Device unit number.
- const **Volcano\_BitField\_t** \***pBitField**: Pointer to the device register field.
- UInt8 \*puData: Data to read.

## 3.17 Volcano\_ReadRegMap

### 3.17.1 Description

Updates the cached register map from the device hardware.

#### 3.17.2 Parameters

- tmUnitSelect\_t tUnit: Device unit number.
- UInt8 uAddress: Data address to read.
- UInt32 uReadLen: Number of data to read (in bytes).

## 4. Description of the structures

## 4.1 SysDependency\_t

This structure contains the following objects:

- IoFunc\_t slo: In/out functions
- TimeFunc\_t sTime: Timer functions

#### 4.2 IoFunc\_t

This structure contains pointers to the following functions:

- tmErrorCode\_t (\*Read): Pointer to the user-written read function (mandatory).
- tmErrorCode\_t (\* Write): Pointer to the user-written write function (mandatory).
- **tmErrorCode\_t** (\* **WriteRead**): Pointer to the user-written write-then-read function (mandatory).

#### 4.3 TimeFunc t

This structure contains pointers to the following functions:

- tmErrorCode\_t (\* Wait): Pointer to the user-written wait function (mandatory).

#### 4.4 Volcano BitField t

This structure contains pointers to the following fields:

- **UInt8 Address**: Register address.
- UInt8 PositionInBits: Bit field position.
- UInt8 WidthInBits: Number of bits in the bit field.
- UInt8 Attributes: Not used.

## 5. Description of the user written functions

The prototypes can be found in the file *Volcano.h*, in the structure type definition of *SysDependency\_t*.

#### 5.1 Read

#### 5.1.1 Prototype

tmErrorCode\_t Read (tmUnitSelect\_t tUnit, UInt32 ReadBitsLen, UInt8\* pData)

#### 5.1.2 Description

This function is currently not used and can remain a dummy function for the user. The Read function is performed through the WriteRead function.

#### 5.2 Write

#### 5.2.1 Prototype

tmErrorCode\_t Write (tmUnitSelect\_t tUnit,UInt32 WriteBitsLen, UInt8\* pData)

#### 5.2.2 Description

This function will be called by the driver to write registers on the BLP25RFE001 device. It returns an error code (0 for no error).

The pData array must contain:

- 2 bits of operand code (00b for write)
- 6 bits of address
- 8 bits of data



<u>Note:</u> the Write function does not need to support the burst mode as it is not used in the BLP25RFE001 driver.

#### 5.2.3 Parameters

- tmUnitSelect\_t tUnit: Device unit number.
- UInt32 WriteBitsLen: Number of bits which must be written.
- Ulnt8\* pData: Table containing operand code, register address and value to write.

#### 5.2.4 Example

```
tmErrorCode_t err;
UInt8 pData[2] = {0x01, 0xBC};
err = Write(0, 16, pData);
```

In this case the Write function must write 0xBC in the register 0x01, on the device identified by the number 0.

#### 5.3 WriteRead

#### 5.3.1 Prototype

**tmErrorCode\_t WriteRead** (tmUnitSelect\_t tUnit, UInt32 WriteBitsLen, UInt8\* pDataWrite, UInt32 ReadBitsLen, UInt8\* pDataRead)

#### 5.3.2 Description

Basically, this function is only used to read registers from the device. This function will be called by the driver to write registers (to send the read operand code and the register address), then read them, on the BLP25RFE001 device. The burst mode is internally

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supported to optimize the read of consecutive bytes, in sending only the first register address.

It returns an error code (0 for no error).

The pDataWrite array must contain:

- 2 bits of operand code (01b for read)
- 6 bits of address
- 8 bits of data (for write operand code only)

The pDataRead array must contain:

- 8 (or more) bits of data



<u>Note:</u> the WriteRead function must support the burst mode for reading as it is implemented in the BLP25RFE001 driver.

#### 5.3.3 Parameters

- tmUnitSelect ttUnit: Device unit number.
- Ulnt32 WriteBitsLen: Number of bits which must be written.
- UInt8\* pDataWrite: Table containing operand code, register address and value to write.
- UInt32 ReadBitsLen: Number of bits which must be read (can be more than one byte).
- UInt8\* pDataRead: Table containing operand code, register address and read value.

#### 5.3.4 Example

```
tmErrorCode_t err;
UInt8 pDataWrite[1] = {0x41};
UInt8 pDataRead[1] = {0xFF};
err = WriteRead(0, 8, pDataWrite, 8, pDataRead);
```

In this case the WriteRead function must write 0x41 to the SPI controller to read the value at the register address 0x01, on the device identified by the number 0. An 8-bit value is stored afterwards in replacing the 0xFF value.

#### **5.4 Wait**

#### 5.4.1 Prototype

tmErrorCode\_t Wait(UInt32 tms)

#### 5.4.2 Description

This function will be called by the driver to wait for a given time in milliseconds.

It returns an error code (0 for no error).

## 5.4.3 Parameters

- UInt32 tms: Time to wait in ms.

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## **5.4.4 Example**

```
tmErrorCode_t err;
err = Wait(10);
```

In this case, the system must wait for 10ms.

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## 6. How to use the BLP25RFE001 driver

## 6.1 Preprocessor definitions to compile the driver

Depending on the platform, the following define may added in the compilation line:

```
BOARD_NXP_OM15000
BOARD_NXP_OM15004C2
BOARD_NXP_SANGO4RF
```

None of them is used for a standard configuration.

#### 6.2 Source files directories

The following source file must be compiled:

```
.\Volcano driver\Volcano.c
```

#### 6.3 Header files directories

The following include directories must be added to the compiling environment:

```
.\inc
.\Volcano_driver\
```

#### 6.4 Header files

The following provided header files must be included:

```
#include "tmNxTypes.h"
#include "tmCompId.h"
#include "tmbslFrontEndTypes.h"
#include "tmFrontEnd.h"
#include "tmUnitParams.h"
#include "tmbslFrontEndCfgItem.h"
#include "Volcano.h"
```

#### 6.5 Customization of the BLP25RFE001

#### 6.5.1 Introduction

The BLP25RFE001 can be customized with the Volcano Local.h file.

It is located in:

```
.\Volcano driver\Volcano Local.h
```

In the *Volcano.c* file, an array of objects *VolcanoObject\_t* is initialized in the function *Volcano\_Open* before the *Volcano\_Hwlnit*. The array name is *gVolcanoInstance[]* and allows to customize one or more devices.

The driver allows up to 4 devices to be controlled. Limiting the driver to less than 4 devices can be achieved in decreasing the define value Volcano\_UNITS (at 4 by default). Allowing more than 4 devices would require to extend the size of the array *gVolcanoInstance[]*.

### 6.5.2 VolcanoObject\_t type

This structure matches the instance of each device. It is filled at driver initialization with *Volcano Open*.

### 6.5.3 Type definition

#### 6.5.3.1 Power State

Initializes PowerStateMode field:

Stand-by mode : Volcano standby

Generator without daisy chaining : Volcano\_generator\_no\_daisy

Generator with daisy chaining : Volcano\_generator\_daisy

Slave with daisy chaining : Volcano\_slave\_daisy

Slave without daisy chaining : Volcano\_slave\_no\_daisy

Generator PPA without daisy chaining : Volcano\_generator\_no\_daisy\_PPA

Generator PPA with daisy chaining : Volcano\_generator\_daisy\_PPA

Slave PPA with daisy chaining : Volcano\_slave\_daisy\_PPA

Slave PPA without daisy chaining : Volcano\_slave\_no\_daisy\_PPA

#### 6.5.3.2 Device Role

Used to configure the device role in the function Volcano\_HwInit.

Master : Volcano\_MasterSlave : Volcano\_Slave

## 6.6 Initialization of the BLP25RFE001

## 6.6.1 Description

The driver is set-up using the function *Volcano\_Open*. This function needs for parameter a structure containing pointers to the functions used for communication and time. The definitions of these functions are given in the structures *tmbslFrontEndloFunc\_t*, *tmbslFrontEndTimeFunc\_t* and *tmbslFrontEndDebugFunc\_t* in the file *tmbslFrontEndtypes.h* provided with the driver.

Only the Read, Write and Wait functions are used.

Once the driver is properly set-up with *Volcano\_Open*, the BLP25RFE001 hardware can be initialized with *Volcano\_Hwlnit*.

#### 6.6.2 Example

Initialize the BLP25RFE001 like a master device (tUnit=0):

```
tmErrorCode_t err = TM_OK;
SysDependency_t sSrvSysFunc; /* setup parameters */

/* Low layer structure to link with user written functions */
sSrvSysFunc.sIo.Write = UserWrittenSPIWrite;
sSrvSysFunc.sIo.WriteRead = UserWrittenSPIWriteRead;
sSrvSysFunc.sTime.Wait = UserWrittenWait;

/* Volcano driver initialization */
err = Volcano_Open(0, 0, &sSrvSysFunc); // master unit 0

/* Hardware init of the master device */
if (err == TM_OK)
    err = Volcano HwInit(0, Volcano Master);
```

## 6.7 How to tune the BLP25RFE001 to a frequency

#### 6.7.1 Description

Once the BLP25RFE001 is initialized, the power state should be appropriate prior to program the device to a selected frequency.

#### 6.7.2 Example

Tune a master BLP25RFE001 (tUnit=0) to 2400 MHz:

```
/* set proper power state */
if (err == TM_OK)
    err = Volcano_SetPowerStateMode(0,
Volcano_generator_no_daisy);

/* set a frequency on the master device */
err = Volcano SetRF(0, 2400000, False); // in kHz
```

## 6.8 Sample code to drive two BLP25RFE001

#### 6.8.1 Description

This is the complete sample code to drive two devices, one master and one slave. The frequency selected on the master will also apply to the slave.

#### 6.8.2 Example

```
tmErrorCode t err = TM OK;
  SysDependency t sSrvSysFunc;
                                 /* setup parameters */
  /* Low layer structure to link with user written functions */
  sSrvSysFunc.sIo.Write = UserWrittenSPIWrite;
  sSrvSysFunc.sIo.WriteRead
                                 = UserWrittenSPIWriteRead;
  sSrvSysFunc.sTime.Wait
                                  = UserWrittenWait;
  /* Driver initialization for master and slave */
  err = Volcano Open(0, 0, &sSrvSysFunc); // master unit 0
  if (err == TM OK)
     err = Volcano Open(1, 1, &sSrvSysFunc); // slave unit 1
  /* Hardware init of the master device */
  if (err == TM OK)
     err = Volcano HwInit(0, Volcano Master);
  /* set proper power state */
  if (err == TM OK)
     err = Volcano SetPowerStateMode(0,
Volcano generator daisy);
```

```
if (err == TM_OK)
    err = Volcano_SetPowerStateMode(1, Volcano_slave_no_daisy);

/* set a frequency on the master device */
err = Volcano_SetRF(0, 2400000, False); // in kHz

/* launch synchro reset all devices master and slave(s) */
if (err == TM_OK)
    err = Volcano_ResetSynchro(0);
if (err == TM_OK)
    err = Volcano_ResetSynchro(1);

/* launch Synchro on slave(s) device(s) */
if (err == TM_OK)
    err = Volcano_SetSynchroSlave(1);

/* launch synchro on master device */
if (err == TM_OK)
    err = Volcano_SetSynchroMaster(0);
```

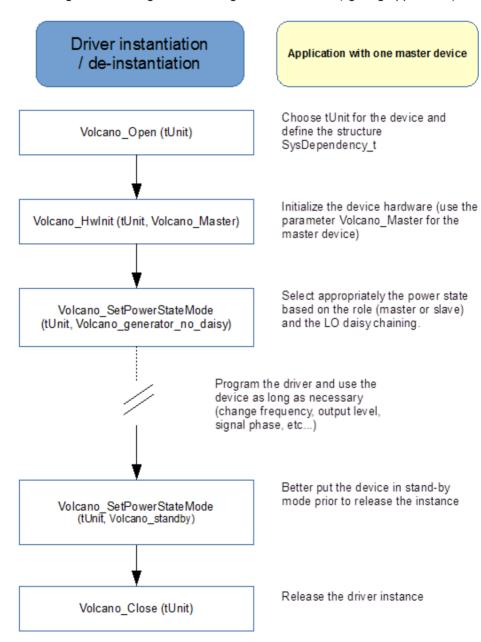
#### 6.9 Return values of the functions

Every function of the driver returns an error message. If the function has been successfully executed the return error message is  $TM_OK$ . If the function was not successfully executed, the error message corresponding to the occurred error is returned. The error messages are listed in the files tmCompld.h provided with the driver.

#### 6.10 Uses cases and flowcharts

#### 6.10.1 Software/hardware initialization

The following flowchart is given for a single master device (lighting application).



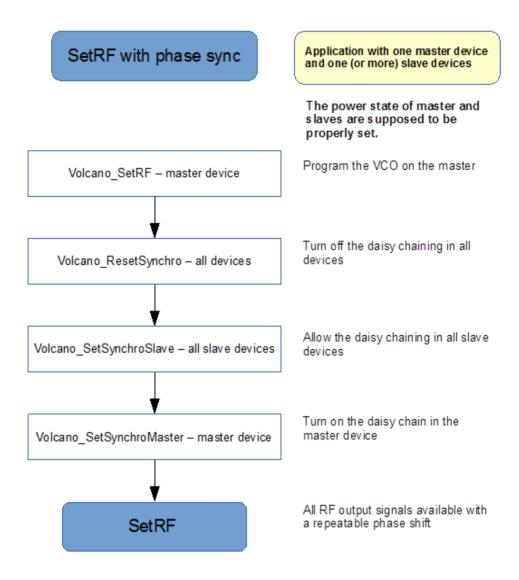
The following flowchart is given for an application with one master device and 3 cascaded slaves (cooking application).

## Driver instantiation Application with one master device and 3 cascaded slave devices / de-instantiation Choose tUnit for each device and Volcano Open - all devices define the structure SysDependency t Initialize the device hardware. Use Volcano HwInit - all devices the parameter : Volcano Master (master device) Volcano Slave (slave devices) Select appropriately the power state based on the role (master or slave) Volcano SetPowerStateMode and the LO daisy chaining: Volcano generator daisy (master) Volcano slave daisy (intermediate slaves) - Volcano slave no daisy (last slave) Program the driver and use the devices as long as necessary (change frequency, output level, signal phase, etc...) Better put the devices in stand-by mode prior to release the instances Volcano SetPowerStateMode (Volcano standby) - all devices Release the driver instances Volcano Close – all devices

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#### 6.10.2 Devices synchronization

In an application with one master and slaves, the master controls the signal frequency for all devices. As long as the phase of each device must be controlled (so to be identical between successive programming), a specific sequence must be followed.



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